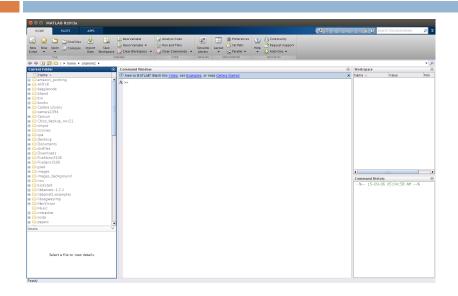
Matlab Introduction

Matlab



Matlab

The startup.m file is a file you create to specify startup options. Use startup.m to modify the default search path, predefine variables in your workspace, or define defaults.

For example, the following statement adds the user-defined folder /home/myname/mytools to the search path.

addpath /home/myname/mytools

Note that it will only read the startup.m file for the folder where Matlab is initialized.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix}$$

- ☐ A Matrix is a rectangular array of numbers.
- $\hfill\Box$ It's size is defined as the number of rows and columns that it contains. e.g. $A_{2\times3}$
- $\hfill\Box$ Elements are accessed by their row, column index. e.g. $A(2,3)=a_{23}$

```
\gg A = rand(2, 3)
A =
   0.8147 0.1270
                       0.6324
   0.9058
             0.9134
                       0.0975
>> size(A)
ans =
    2
          3
>> A(2,3)
ans =
    0.0975
```

```
>> A(:,2)
ans =
     0.1270
     0.9134

>> A(2,:)
ans =
     0.9058     0.9134     0.0975
```

Matrix Addition

A and B are $m \times n$ matrices, A + B is an $m \times n$ matrix defined as:

$$A + B = A_{ij} + B_{ij}$$

Porperties:

- □ Associative property: (A + B) + C = A + (B + C)
- \square Commutative property: A + B = B + A

Matrix Addition

```
>> A = rand(2,3)
A =
   0.2785
            0.9575
                      0.1576
   0.5469
            0.9649
                      0.9706
>> B = rand(2,3)
B =
            0.8003
                     0.4218
   0.9572
   0.4854
            0.1419
                      0.9157
>> A + B
ans =
   1.2357
            1.7578
                      0.5794
   1.0323
            1.1068
                      1.8863
```

Scalar Multiplication

Given an $m \times n$ matrix A and a scalar α , $\alpha A = A\alpha$ is an $m \times n$ matrix defined as:

$$(\alpha A)_{ij} = \alpha \times A_{ij}$$

Properties:

- \square Associative: $(\alpha\beta)A = \alpha(\beta A)$
- □ Distributive:
 - $\square \ \alpha(A+B) = \alpha A + \alpha B$
 - $\square (\alpha + \beta)A = \alpha A + \beta A$

Matrix Multiplication

Given $A_{m \times p}$ and $B_{p \times n}$, AB is an $m \times n$ matrix defined as:

$$(AB)_{ij} = \sum_{k=1}^{p} A_{ik} B_{kj}$$

 $\mathsf{A}\mathsf{B}$ is defined only when the number of columns of A equals the number of rows of B

Matrix Multiplication

$$A_{(m \times p)}B_{(p \times n)} = AB_{(m \times n)}$$

Properties:

- Matrix multiplication is not commutative
- □ Distributive:
 - \square A(B+C) = AB + AC
- \square Associative: A(BC) = (AB)C
- $\square (AB)^T = B^T A^T$

Matrix Multiplication

Transpose

Given $A_{m \times x}$, its transpose A^T is an $n \times m$ matrix defined as:

$$(A^{T})_{ij} = A_{ij}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^{T} = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

Properties:

- \square $(A^T)^T = A$
- $\Box (A+B)^T = A^T + B^T$
- $\square (\alpha A)^T = \alpha A^T$

>> A'

Variables

To see a list of your variables use the who or whos commands.

Bytes Class Attributes

>> who
Your variables are:
A B ans
>> whos
Name Size

		3	
A	2x3	48	double
В	3x2	48	double
ans	2x2	32	double

Some useful ways to create matrices

```
>> B = reshape([1:1:9], 3, 3);
>> a = [1; 4; 7];
>> b = [2; 5; 8];
>> c = [3; 6; 9];
>> A = [a, b, c]
A =

    1     2     3
    4     5     6
    7     8     9
```

Saving State

- □ To save the current variables: save filename
- □ To load variables from a file: load filename

Scripts

Any *.m file in your path can be run in Matlab by simply typing it's name.

You can add and remove directories to the path using the addpath and rmpath commands. e.g. :

- >> addpath ~/CMPUT340
- >> rmpath ~/CMPUT340

Variables created in script files will be kept in the current workspace.

Functions

Functions are declared in .m files that are named after the function you are creating. Multiple functions can be placed in one .m file, however only the one named the same as the file will be exposed.

```
function [r1, r2] = foo(p1, p2)
    r1 = p1 * p2;
    local_var = p1 + p2;
    r2 = local_var * 2
end
```

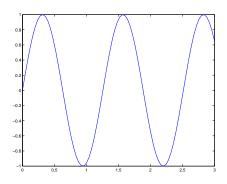
Variables created within the function do not persist after being called.

Control Statements: If

```
1 if a > 5
2  disp('hi')
3 else
4  disp('bye')
5 end;
```

Plots

```
1 n = 25;
2 x = 0:1/n:3;
3 y = sin(5*x);
4 plot(x,y);
5 print -depsc sin.eps;
```



Other useful commands

For information on any of	these simply use: help <command/>
□ clear	□ size
□ clc	□ plot3
□ ones	□ hold
□ eye	□ scatter
□ zeros	

P1: Exercise 1

```
1 % Vectorize the following
2 % Note the use of the tic/toc calls to time execution
3 % Compare the time once you have vectorized it
5 tic
6 \text{ for } i = 1:1000
      t(i) = 2*i;
      y(i) = \sin(t(i));
9 end
10 toc
11
12 clear;
```

References

- PEKALSKA, E., VAN DER GLAS, M., SERLIE, I., AND VOSSEPOEL, A. Introduction to MATLAB.
 University of Twente, Department of Applied Mathematics, 2006.
- [2] SCHUURMANS, D. CMPUT 340 Reference Material. https://eclass.srv.ualberta.ca/mod/page/view.php?id=1128238, 2014.